

Can you read this?

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## Chapter 2

Time series regression

$$y_t = \beta_0 + \beta_1 x_{1t} + \dots + \beta_q x_{qt} + w_t$$

where  $w_t \sim WN(\sigma_w^2)$

Usual results of regression apply.

If  $w_t$  is not white noise, estimates are consistent but standard errors are wrong.

- autocorrelation
- heteroskedasticity

Example: Estimating a time trend

## Assessing model fit

- Akaike Information Criterion (AIC)

$$AIC = \log \hat{\sigma}^2 + \frac{n+2k}{n}$$

$$\text{or } AIC = -2 \log L + 2k$$

where  $k$  is the number estimated model parameters.

Prefer model with minimum AIC.

- Bias corrected AIC

$$AIC_c = \log \hat{\sigma}^2 + \frac{n+k}{n-k-2}$$

$2k??$

- Bayesian Information Criterion (BIC)  
also known as Schwarz Criterion

$$BIC = \log \hat{\sigma}^2 + \frac{k \log n}{n}$$

or

$$BIC = -2 \log L + k (\log(n) - \log(2\pi))$$

In order to do anything useful, we would like to have a stationary process.

Example: stationary about a time trend

$$x_t = \mu_t + y_t$$

where  $y_t$  is stationary.

Typically, might estimate  $\mu_t$  and work

$$\hat{y}_t = x_t - \hat{\mu}_t.$$

Another way to get stationarity is to difference the data.

given  $\{x_t\}$ , construct

$$\begin{aligned} y_t &= x_t - x_{t-1} \\ &= \nabla x_t \end{aligned}$$

### Differencing

Theorem: If  $x_t$  is stationary, then so is  $\nabla x_t$ .

(differencing preserves stationarity)

$$\text{proof: } E[\nabla x_t] = E[x_t - x_{t-1}] = E[x_t] - E[x_{t-1}] = \mu_x - \mu_x = 0$$

$$\text{Cov}(\nabla x_t, \nabla x_s) = E[(x_t - x_{t-1})(x_s - x_{s-1})]$$

$$= \text{Cov}(x_t, x_s) - \text{Cov}(x_t, x_{s-1}) - \text{Cov}(x_{t-1}, x_s) + \text{Cov}(x_{t-1}, x_{s-1})$$

Let  $h = s - t$

$$= \gamma_x(h) - \gamma_x(h-1) - \gamma_x(h+1) + \gamma_x(h)$$

$$= 2\gamma_x(h) - \gamma_x(h-1) - \gamma_x(h+1)$$

$E[\nabla x_t]$  is constant &  $\text{Cov}(\nabla x_t, \nabla x_s)$  depends only on  $s-t$ . So stationary.