

↳ AR - Autoregression

$$X_t = \alpha_0 + \alpha_1 X_{t-1} + \dots + \alpha_p X_{t-p} + w_t$$

where  $w_t \sim WN(\sigma_w^2)$

↳ example

$$X_t = X_{t-1} - 0.9 X_{t-2} + w_t$$

where  $w_t \sim WN(0.01)$

Random walk  $\|w_t\| < \infty$

$$X_t = X_{t-1} + w_t$$

where  $w_t \sim WN(\sigma_w^2)$

$$X_0 = X_0$$

$$X_t = (X_{t-2} + w_{t-1}) + w_t$$

$$\begin{aligned} X_t &= \left( \underbrace{X_{t-1}}_{(X_{t-2} + w_{t-1})} + w_t \right) \\ &= \left( \left( \left( X_{t-3} + w_{t-2} \right) + w_{t-1} \right) + w_t \right) \\ &= \left( \left( \left( \left( X_{t-4} + w_{t-3} \right) + w_{t-2} \right) + w_{t-1} \right) + w_t \right) \\ &\quad \vdots \end{aligned}$$

$$= X_0 + \sum_{j=1}^t w_j$$

Random walk with drift

$$X_t = \delta + X_{t-1} + w_t$$

where  $w_t \sim WN(\delta, \sigma_w^2)$

$$X_0 = X_0$$

$$X_t = \delta + \left( \delta + X_{t-2} + w_{t-1} \right) + w_t$$

$$= \delta + \left( \delta + \left( \delta + X_{t-3} + w_{t-2} \right) + w_{t-1} \right) + w_t$$

⋮

$$\begin{aligned} & \vdots \\ \hat{X}_t &= \int_t + \sum_{i=1}^t \omega_i \\ & \quad \swarrow \\ & \quad \uparrow \\ & \quad d_n = \frac{p}{t} \end{aligned}$$

Signal plus noise

$$y_t = s_t + w_t$$

↑                      ↖  
Signal                      noise

Example

$$s_t = A \cos(2\pi\omega t + \varphi)$$

$A$  = amplitude

$\omega$  = frequency

$\varphi$  = shift

Try this with  $A=2$ ,  $\omega=1/50$ ,  $\varphi=0.6\pi$

Given a time series  $\{x_1, x_2, \dots, x_t\}$

Recall that a complete description involves the joint CDF

$$F(x_1, x_2, \dots, x_t).$$

But presently in practice it is sufficient to just be concerned with means & COVARIANCES.

Def: The mean function is

$$\mu_{x_t} = E[x_t]$$

Example

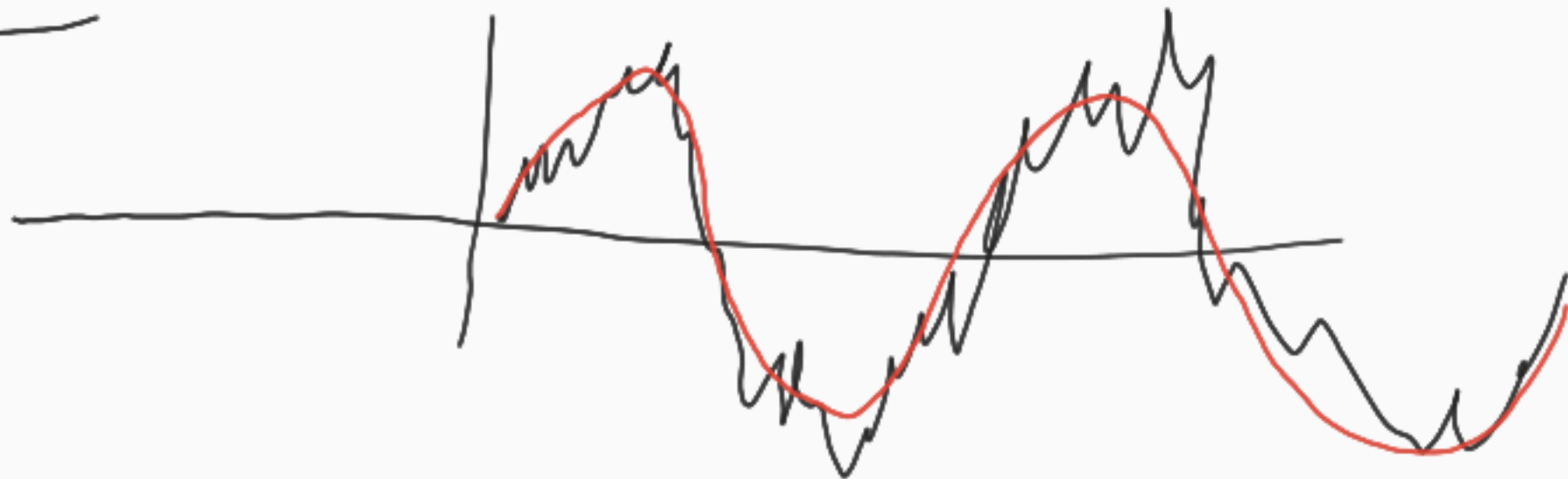
$$X_t = \sin(2\pi t/50) + w_t$$

$$M_{Xt} = \sin(2\pi t/50)$$

If there is no ambiguity, omit the subscript  $x$ :

$$M_t = \sin(2\pi t/50)$$

$S_t = M_t$                        
 $X_t$                      



Def: The autocovariance function is

$$\gamma_x(s, t) = \text{COV}(X_s, X_t) = \mathbb{E}[(X_s - \mu_s)(X_t - \mu_t)]$$

Autocovariance measures linear dependence between two observations of same series taken at different points in time.

Remember: Two random variables can be dependent even if they are

Note that  $\gamma_x(t, t) = \text{COV}(X_t, X_t) = \text{Var}(X_t)$  uncorrelated!

Def: The autocorrelation fn is

$$\rho_x(s, t) = \frac{\gamma_x(s, t)}{\sqrt{\gamma_x(s, s) \gamma_x(t, t)}}$$

Example

$$x_t = 2 \sin(2\pi t / 50) + w_t$$

$$m_t = 2 \sin(2\pi t / 50)$$

$$\gamma_x(s, t) = E \left[ (x_s - m_s)(x_t - m_t) \right] = E \left[ w_s \cdot w_t \right] = \begin{cases} \sigma_w^2 & s = t \\ 0 & \text{otherwise} \end{cases}$$

Def :  $\{X_1, X_2, \dots\}$  is (weakly) stationary if

$$\mu_t = \mu_s \quad \text{for} \quad s, t = 1, 2, \dots$$

and

$$\gamma(s, t) = \gamma(s+h, t+h)$$

for all  $s, t = 1, 2, \dots$   
and  $h > 0$ .

In this case we can simply write

$$\mu = E[X_t]$$

$$\gamma_h = \gamma(t, t+h)$$

Don't need to  
indicate time  $t$