

## ACF of AR(2)

Assume causal

$$y_t = \varphi_1 y_{t-1} + \varphi_2 y_{t-2} + w_t$$

$$\delta_h = \varphi_1 \delta_{h-1} + \varphi_2 \delta_{h-2} \quad h = 1, 2, 3, \dots$$

↑

difference equation.

Initial conditions given by solving  
Yule-Walker equations.

$$\left. \begin{aligned} \delta_0 &= \varphi_1 \delta_1 + \varphi_2 \delta_2 + \sigma_w^2 \\ \delta_1 &= \varphi_1 \delta_0 + \varphi_2 \delta_1 \\ \delta_2 &= \varphi_1 \delta_1 + \varphi_2 \delta_0 \end{aligned} \right\} \begin{array}{l} \text{3 eq's in} \\ \text{3 unknowns} \\ \text{(assumes } \sigma_w^2 \\ \text{is known).} \end{array}$$

In practice, this can be done slightly more easily

$$\rho_0 = 1$$

$$\rho_1 = \varphi_1 \rho_0 + \varphi_2 \rho_{-1}$$

$$= \frac{\varphi_1}{1 - \varphi_2}$$

Example:

$$y_t = \frac{3}{2} y_{t-1} - \frac{3}{4} y_{t-2} + w_t$$

$$\varphi(z) = 1 - \frac{3}{2}z + \frac{3}{4}z^2$$

$$\text{roots: } z = 1 \pm \frac{i}{\sqrt{3}}$$

outside unit circle so causal.

$$\rho_0 = 1$$

$$\rho_1 = \frac{\varphi_1}{1 - \varphi_2} = \frac{3/2}{1 - 3/4} = 6/7$$

$$\rho_h = \varphi_1 \rho_{h-1} + \varphi_2 \rho_{h-2} \quad h=2, 3, \dots$$

Now simulate data from this model,  
compute sample ACF, theoretical ACF & plot.

### ACF of AR(p)

$$y_t = \varphi_1 y_{t-1} + \dots + \varphi_p y_{t-p} + w_t$$

ACF is given by difference equation

$$\gamma_h = \varphi_1 \gamma_{h-1} + \dots + \varphi_p \gamma_{h-p} \quad h=1, 2, 3, \dots$$

with initial given by solving Yule-Walker equations (recognizing  $\gamma_h = \gamma_{-h}$ )

$$\left. \begin{array}{l} p+1 \text{ eq's in} \\ p+1 \text{ unknowns} \end{array} \right\} \begin{array}{l} \gamma_0 = \varphi_1 \gamma_{-1} + \dots + \varphi_p \gamma_{-p} + \sigma_w^2 \\ \gamma_1 = \varphi_1 \gamma_0 + \dots + \varphi_p \gamma_{1-p} \\ \vdots \\ \gamma_p = \varphi_1 \gamma_{p-1} + \dots + \varphi_p \gamma_0 \end{array}$$

## ACF of $MA(1)$

$$y_t = w_t + \theta w_{t-1}$$

$$\begin{aligned}\gamma_0 &= E[y_t y_t] = E[(w_t + \theta w_{t-1})(w_t + \theta w_{t-1})] \\ &= \sigma_w^2 + \theta^2 \sigma_w^2 = (1 + \theta^2) \sigma_w^2\end{aligned}$$

$$\begin{aligned}\gamma_1 = \gamma_{-1} &= E[y_t \cdot y_{t-1}] = E[(w_t + \theta w_{t-1})(w_{t-1} + \theta w_{t-2})] \\ &= \theta \sigma_w^2\end{aligned}$$

$$\gamma_h = 0 \quad \text{for } h = \pm 2, \pm 3, \dots$$

# ACF of MA( $\ell$ )

$$y_t = \sum_{j=0}^{\ell} \theta_j w_{t-j}$$

Assume  $h > 0$

$$\gamma(-h) = \gamma(h) = E[y_{t-h} \cdot y_t]$$

$$= E \left[ \left( \sum_{j=0}^{\ell} \theta_j w_{t-h-j} \right) \left( \sum_{k=0}^{\ell} \theta_k w_{t-k} \right) \right]$$

$$= \begin{cases} \sigma_w^2 \sum_{j=0}^{\ell-h} \theta_j \theta_{j+h} & 0 \leq h \leq \ell \\ 0 & \text{else} \end{cases}$$

## ACF of ARMA(1,1)

$$y_t = \varphi y_{t-1} + w_t + \theta w_{t-1}$$

Assume causal. So, we can write

$$y_t = \sum_{j=0}^{\infty} \psi_j w_{t-j}$$

Notice that

$$\begin{aligned} E[y_t \cdot w_t] &= E \left[ \left( \sum_{j=0}^{\infty} \psi_j w_{t-j} \right) \cdot w_t \right] \\ &= \sigma_w^2 \cdot \psi_0 \end{aligned}$$

$$\begin{aligned} E[y_t \cdot w_{t-1}] &= E \left[ \left( \sum_{j=0}^{\infty} \psi_j w_{t-j} \right) \cdot w_{t-1} \right] \\ &= \sigma_w^2 \psi_1 \end{aligned}$$

⋮

$$E[y_t \cdot w_{t-h}] = \begin{cases} \sigma_w^2 \psi_h & \text{for } h \geq 0 \\ 0 & \text{for } h < 0 \end{cases}$$

Now let's compute the ACF.

$$\begin{aligned} \gamma_{-h} = \gamma_h &= E[y_t \cdot y_{t+h}] \\ &= E \left[ y_t \cdot \left( \varphi y_{t+h-1} + w_{t+h} + \theta w_{t+h-1} \right) \right] \\ &= E \left[ \dots \right] \end{aligned}$$

$$= \varphi E[y_t - y_{t+h-1}] + E[y_t w_{t+h}] + \theta E[y_t w_{t+h-1}]$$

for  $h=2, 3, \dots$

$$\gamma_h = \varphi \gamma_{h-1} + 0 + 0$$

$$\left. \begin{array}{l} h=0 \quad \gamma_0 = \varphi \gamma_1 + \psi_0 \sigma_w^2 + \theta \psi_1 \sigma_w^2 \\ h=1 \quad \gamma_1 = \varphi \gamma_0 + 0 + \theta \psi_0 \sigma_w^2 \end{array} \right\} \text{Yule-Walker}$$

Note that this is the same as for the AR(1) but with different initial conditions (given by solving the Yule-Walker equations).

## ARMA (p, q)

$$y_t = \varphi_1 y_{t-1} + \dots + \varphi_p y_{t-p} + w_t + \theta_1 w_{t-1} + \dots + \theta_q w_{t-q}$$

$$\delta_h = E \left[ y_t \cdot y_{t+h} \right]$$

= ...

As before, we get

$$\delta_h = \varphi_1 \delta_{h-1} + \dots + \varphi_p \delta_{h-p} \quad \text{for } h > q$$

With initial conditions given by solving the Yule-Walker equations:

$$\delta_h = \varphi_1 \delta_{h-1} + \dots + \varphi_p \delta_{h-p} + \sigma_w^2 \sum_{i=0}^q \theta_i \delta_{h-i}$$

for  $h=0, 1, 2, \dots, p$

# PACF

Given  $\{y_t\}$  (assume  $\mu_y = 0$ ).

Consider the population regression

$$y_t = \varphi_{i1} y_{t-1} + \dots + \varphi_{ii} y_{t-i} + \varepsilon_t$$

where

$$\begin{pmatrix} \varphi_{i1} \\ \vdots \\ \varphi_{ii} \end{pmatrix} \stackrel{\text{def}}{=} \left[ E(\mathbf{X}'\mathbf{X}) \right]^{-1} E(\mathbf{X}'\mathbf{Y})$$

$$\text{with } \mathbf{X} = (y_{t-1}, \dots, y_{t-i})$$

$$\mathbf{Y} = y_t$$

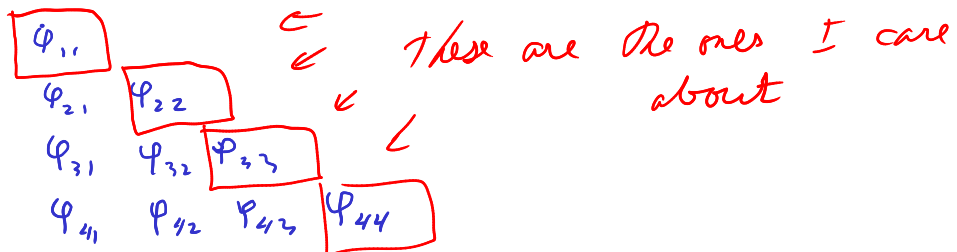
This is also called "linear projection."

We refer to  $\varphi_{ii}$  as the  $i^{\text{th}}$  PACF.

We can think of  $\rho_i$  as being motivated by the <sup>univariate</sup> regression  $y_t = \rho_i y_{t-i} + \varepsilon_t$

$\varphi_{ii}$  is motivated by the multivariate regression

$$y_t = \varphi_{i1} y_{t-1} + \dots + \varphi_{ii} y_{t-i} + \varepsilon_t$$



$$y_t = \varphi_{11} y_{t-1} + \varepsilon_t$$

$$y_t = \varphi_{21} y_{t-1} + \varphi_{22} y_{t-2} + \varepsilon_t$$

$$y_t = \varphi_{31} y_{t-1} + \varphi_{32} y_{t-2} + \varphi_{33} y_{t-3} + \varepsilon_t$$

To estimate  $\varphi_{ii}$  given  $\{y_t\}$

do the regression

$$y_t = \hat{\varphi}_{i1} y_{t-1} + \dots + \hat{\varphi}_{ii} y_{t-i} + \varepsilon_t$$

↑  
this is the  $i$ th Partial  
autocorrelation.

Example:

given the AR(2) model,

$$x_t = \frac{3}{2} x_{t-1} - \frac{3}{4} x_{t-2} + w_t$$

(1) is it causal?

(2) compute & plot theoretical ACF & PACF

(3) simulate 1000 observations & plot sample

ACF & PACF

## Summary

AR( $p$ ): ACF decays exponentially  
PACF cuts off after  $p$  lags

MA( $q$ ): ACF cuts off after  $q$  lags  
PACF decays exponentially

So, given data, behavior of ACF & PACF  
can be used in the process of model  
exploration.